# Datasheet Variable frequency drive VYBO Electric a.s.



## Typ: V900-4T2500



| Typ. 7700 TT2000                                     | -  |
|--|--|
| Rated power  | 250 kW   |
| Rated output current                                 | 470 A  |
| Supply voltage                                       | 3 x 400 V  |
| Output voltage                                       | 0 – 400 V  |
| Output frequency                                     | 0 – 600 Hz   |
| Overload capacity in ND mode - Normal load (N. Duty) | 120% / 60 s  |
| Overloading in HD mode - Heavy load (H. Duty)        | 150% / 60 s  |
| Control mode V/F scalar control                      | <ul> <li></li> </ul>   |
| Open-loop vector SFVC control mode                   | <ul> <li></li> </ul>   |
| Closed-loop vector CLVC control mode                 | <ul> <li></li> </ul>   |
| Analog inputs  | 2  |
| Digital inputs                                       | 6  |
| Analog outputs                                       | 2  |
| Relay outputs  | 2  |
| Open collector outputs                               | 1  |
| Brake transistor                                     | ×  |
| EMC filter   | ✓  |
| +10 V output   | ✓<br>✓   |
| +24 V output   | <ul> <li></li> </ul>   |
| Input for PTC  | <ul> <li></li> </ul>   |
| Safe Torque Off (STO)                                | ×  |
| Emergency STOP (EMS)                                 | <ul> <li></li> </ul>   |
| Integrated Ethernet                                  | ×  |
| Integrated MODBUS RTU                                | <ul> <li></li> </ul>   |
| PROFINET   | <ul> <li>✓</li> </ul>  |
| PG card for encoder                                  | <ul> <li></li> </ul>   |
| PID  | <b>~</b>   |
| PLC intelligent function                             | <ul> <li></li> </ul>   |
| External panel connection (normally up to 30 m)      | ×  |
| Degree of protection IP 20                           | ✓  |
| Degree of protection IP 65                           | ×  |
| Change of direction of rotation via external input   | <ul> <li>Image: A second s</li></ul> |
| Change of direction of rotation from the panel       | <ul> <li>✓</li> </ul>  |

#### Detailed specification

| VFD model type V900 | Rated<br>output<br>power<br>(kW) | Maximum input current (A) | Rated output current<br>(A) | Recommended<br>motor power<br>(kW) |
|---------------------|----------------------------------|---------------------------|-----------------------------|------------------------------------|
| V900-4T2500         | 250                              | 475                       | 470                         | 250                                |

| Input voltage (V) | Power | Cross section of the voltage | Recommended circuit breaker (A) |
|-------------------|-------|------------------------------|---------------------------------|
| 50/60Hz           | (kW)  | cable (mm²)                  |                                 |
| 3 phase 3 x 400 V | 250   | 240                          | 630                             |

## Table of suitable braking resistors

|             |                           | Braking resistance       |               |                           |
|-------------|---------------------------|--------------------------|---------------|---------------------------|
| Type of VFD | Resistor<br>power<br>(kW) | Resistance value (Ω) (≥) | Braking unit  | Recommended<br>power (kW) |
| V900-4T2500 | 21*2                      | 2,5*2                    | 21000W-2.5R*2 | 250                       |

## General technical parameters for all types of V900

|                            | Input voltage range: 1 x 230 V AC ± 10 %               |  |
|----------------------------|--|--|
| Power supply               | 3 x 400 V AC ± 10 %                                    |  |
| Input frequency resolution | Power frequency range: 47 to 63 Hz                     |  |
|                            | V/F control  |  |
| Control mode               | SFVC vector control with open circuit                  |  |
|                            | CLVC vector control with closed circuit (above 4,0 kW) |  |
| Maximum frequency          | 0 - 600 Hz   |  |
| Carrier frequency          | 0.5 kHz - 8 kHz  |  |
|                            | The carrier frequency is automatically set             |  |
|                            | based on the load characteristic.                      |  |
| Input frequency resolution | Digital setting 0.01 Hz                                |  |
|                            | Analog setting: maximum frequency x 0.025%             |  |
|                            | G type: 0.5 Hz / 150 % (SFVC)                          |  |
| Initial torque             | P type: 0.5 Hz / 180 % (CLVC)                          |  |
|                            | P type: 0.5 Hz / 100 %                                 |  |
| Speed range                | 1:100 (SVC) 1:1000 (CLVC)                              |  |

| Speed stability                       | ± 0,5 % (SVC) ±0,2% (CLVC)  |
|---------------------------------------|---|
| Overloadability                       | G type: 60s for 150% of rated current, 3s for 180% rated current  |
|                                       | P typy: 60s for 120% of rated current, 3s for 150% of rated current   |
| Increase torque                       | Automatic torque increase or  |
|                                       | manual increase by user from 0,1 % to 30,0 %  |
|                                       | Linear V/F curve  |
| V/F curve                             | Multipoint V/F curve  |
| V/F CUIVE                             | N-voltage V/F curve (multiple 1,2*voltage, 1,4*voltage,   |
|                                       | 1,6*voltage, 1,8*voltage, square)   |
| V/F separation                        | Two types: full separation; half separation   |
| Damp modes                            | Linear ramp   |
| Ramp modes                            | 4 groups of acceleration / deceleration times with a range of 0.0-6500.0 s  |
|                                       | Braking frequency: 0.0 Hz to maximum frequency  |
| DC braking                            | Braking time: 0.0-36.0 s  |
|                                       | Braking current value: 0.0% -100.0%   |
| Control in JOG mode                   | JOG frequency range: 0.00-50.00 Hz  |
| (stepping)                            | JOG acceleration / deceleration time: 0.0-6500.0 s  |
|                                       | Implemented up to 16 speeds using   |
| Simple PLC, multiple preset<br>speeds | a simple PLC function or combination of   |
| opeede                                | end states of clamps  |
| Built-in PID regulator                | Facilitates a process-controlled closed-loop control system.  |
| Automatic voltage                     | It can automatically maintain a constant output voltage   |
| regulation (AVR)                      | when the supply voltage changes.  |
| Overvoltage and overcurrent control   | Current and voltage are automatically limited during operation to prevent frequent tripping due to overvoltage and overcurrent. |
| Fast limit of current                 | Helps prevent common errors due to AC motor overcurrent   |
|                                       | It can automatically limit the torque and prevent frequent  |
| Torque and steering limitation        | overcurrent change during running. Torque control can be  |
|                                       | implemented in CLVC mode  |
| High performance                      | AC motor control is performed by high-performance   |
|                                       | vector current control technology.  |
|                                       | Support for differential input PG card, resolver PG card, rotary  |
|                                       | transformer PG card, etc.   |
| PG card support                       | PG cards can be connected to models V900-4T0040 and larger  |
|                                       | PG cards can be connected to models V900-2S0040 and 2S0055  |

|                               | "Emergency Stop" system: in case of emergency, stops the   |
|-------------------------------|--|
| STO safety function           | inverter immediately, after activating the J4 switch on the STO.   |
| PTC motor temperature control | Input for PTC motor or thermal contact protection.   |
| Time management               | Time range: 0 - 6500 minutes   |
| Communication protocol        | MODBUS RTU; PROFINET   |
|                               | Control panel / Control terminals / Serial communication port  |
| Boot Command Channel          | You can switch between these sources in different ways.  |
|                               | 10 kinds of frequencies , Setting digital, analog voltage, analog  |
| Frequency source              | current, pulse, serial port. You can switch between these sources  |
|                               | in different ways.   |
|                               | 10 kinds of frequencies. Allows fine tuning of auxiliary frequency   |
| Auxiliary frequency source    | and frequency synthesis.   |
|                               | 5 digital inputs for types 0,4 - 5,5 kW  |
|                               | 1 analog input for types 0,4 - 5,5 kW  |
| Input terminals               | 6 digital inputs for types above 7,5 kW  |
|                               | 2 analog inputs for types above 7,5 kW   |
|                               | 1 high-speed pulse output (open collector)   |
|                               | 1 relay output for types 0,4 - 5,5 kW  |
|                               | 1 analog output for models 0,4 - 5,5 kW  |
| Output terminals              | 2 relay outputs for types 7,5 - 500 kW   |
|                               | 2 analog outputs for performance 7,5 - 500 kW  |
|                               | 1 high-speed pulse output (open collector)   |
| EMC (compatibility)           | IE 61000-4-6; IEC 61000-4-4; IEC 61000-4-11; IEC 61000-4-5   |
|                               | EN/IEC 61800-3:2017; C1, which is suitable for the 1st environment;  |
| Standards                     | EN/IEC 61800-3:2017; C2, which is suitable for the 1st environment;  |
| LED display                   | Displays parameters  |
| Lock keys and select features | Can block buttons partially or completely and define the range of functions of some buttons to prevent malfunctions. |
|                               | Motor short-circuit detection at power-up, input/output phase loss   |
| Protection mode               | protection, over-current protection, over-voltage protection, under-   |
|                               | voltage protection, over-temperature protection and overload   |
|                               | protection.  |
|                               | Install indoors, avoid direct sunlight, salt, dust,  |
| la chelline d                 | corrosive or flammable gas, smoke, steam.  |
| Installing in an environment  | Resistance to chemical contaminants class 3C3 EN/IEC 60721-3-3   |
|                               | Dust pollution resistance 3S3EN/IEC 60721-3-3.   |

| Height above sea level | Under 1000 m n.m (reduce the power when used above 1000 m.n.m.) |
|------------------------|---|
| Ambient temperature    | -10 °C - 40 °C (reduce the power when used above                |
|                        | 40 °C (max. to 50 °C)   |
| Humidity               | Less than 95% relative humidity, no condensation IEC 60068-2-3  |
| Vibration              | Less than 5,9 m/s2 (0,6g) IEC 60068-2-6                         |
| Storage temperature    | - 20 °C to + 60°C   |

